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<u>L25</u>	L22 and l8	18	<u>L25</u>
<u>L24</u>	L22 and l7	81	<u>L24</u>
<u>L23</u>	L22 and l6	240	<u>L23</u>
<u>L22</u>	L21 and (column\$1 or row\$1) near8 (locat\$6 or address\$3)	2626	<u>L22</u>
<u>L21</u>	L20 and vector\$1	18614	<u>L21</u>
<u>L20</u>	point\$3 near5 (array\$1 or list\$3 or group\$4)	117878	<u>L20</u>
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<u>L19</u>	l4 and l8	0	<u>L19</u>
<u>L18</u>	l4 and l6	4	<u>L18</u>
<u>L17</u>	l3 and l8	0	<u>L17</u>
<u>L16</u>	l3 and l7	4	<u>L16</u>

<u>L15</u>	l3 and l6	14	<u>L15</u>
<u>L14</u>	l2 and l8	1	<u>L14</u>
<u>L13</u>	l2 and l7	9	<u>L13</u>
<u>L12</u>	l2 and l6	27	<u>L12</u>
<u>L11</u>	l1 and l8	20	<u>L11</u>
<u>L10</u>	l1 and l7	127	<u>L10</u>
<u>L9</u>	l1 and l6	263	<u>L9</u>
<u>L8</u>	(711/213-217)![CCLS]	1225	<u>L8</u>
<u>L7</u>	(712/2-22)[CCLS]	1706	<u>L7</u>
<u>L6</u>	(712/2-300)[CCLS]	11684	<u>L6</u>
<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=OR</i>			
<u>L5</u>	l3 and (column\$1 or row\$1) near8 (locat\$6 or address\$3)	11	<u>L5</u>
<u>L4</u>	L3 and (arbitr\$6 or random\$3) near8 (locat\$6 or address\$3)	16	<u>L4</u>
<u>L3</u>	L2 near25 entr\$4	65	<u>L3</u>
<u>L2</u>	L1 near25 (id\$1 or identif\$7)	393	<u>L2</u>
<u>L1</u>	vector\$1 near25 (locat\$6 or point\$4 or address\$3 or index\$3 or indices) near8 (array\$1 or list\$3 or group\$4)	4482	<u>L1</u>

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IEE JNL IEE Journal or Magazine

IEEE CNF IEEE Conference Proceeding

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 Cardoso, J.F.; Souloumiac, A.;
 Radar and Signal Processing, IEE Proceedings F
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- ☐ 3. **Issues on the IP multicast service behaviour over the next-generation satellite-terrestrial hyl**
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- ☐ 4. **Instability in DOA manifold ambiguity resolution**
 Abramovich, Y.I.; Spencer, N.K.; Gaitsgory, V.G.;
 Signal Processing and Its Applications, 1999. ISSPA '99. Proceedings of the Fifth International Syn
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- ☐ 5. **Parallel algorithm for determining motion vectors in ice floe images by matching edge featur**
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- ☐ 6. **Vector control for airborne phased array radar**
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